

Geostatistical-Inspired Metamodeling and Optimization of Nano-CMOS Circuits

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Outline of the talk

- Background and Motivation
- Related Prior Research
- Thermal Sensors
- Proposed Design Optimization Flow Methodology
- Experimental Results
- Conclusions and Future Research Directions

Issues in NanoCMOS Design

- Expensive Computer Simulations
- Pronounced effects of process variations in deep nanometer regions
 - Increase in design parameters
 - Current modeling techniques unable to capture effects of process variation

Background and Motivation

- Complex and High density designs
- Design for low power consumption
- Reliability issues
 - Thermal monitoring

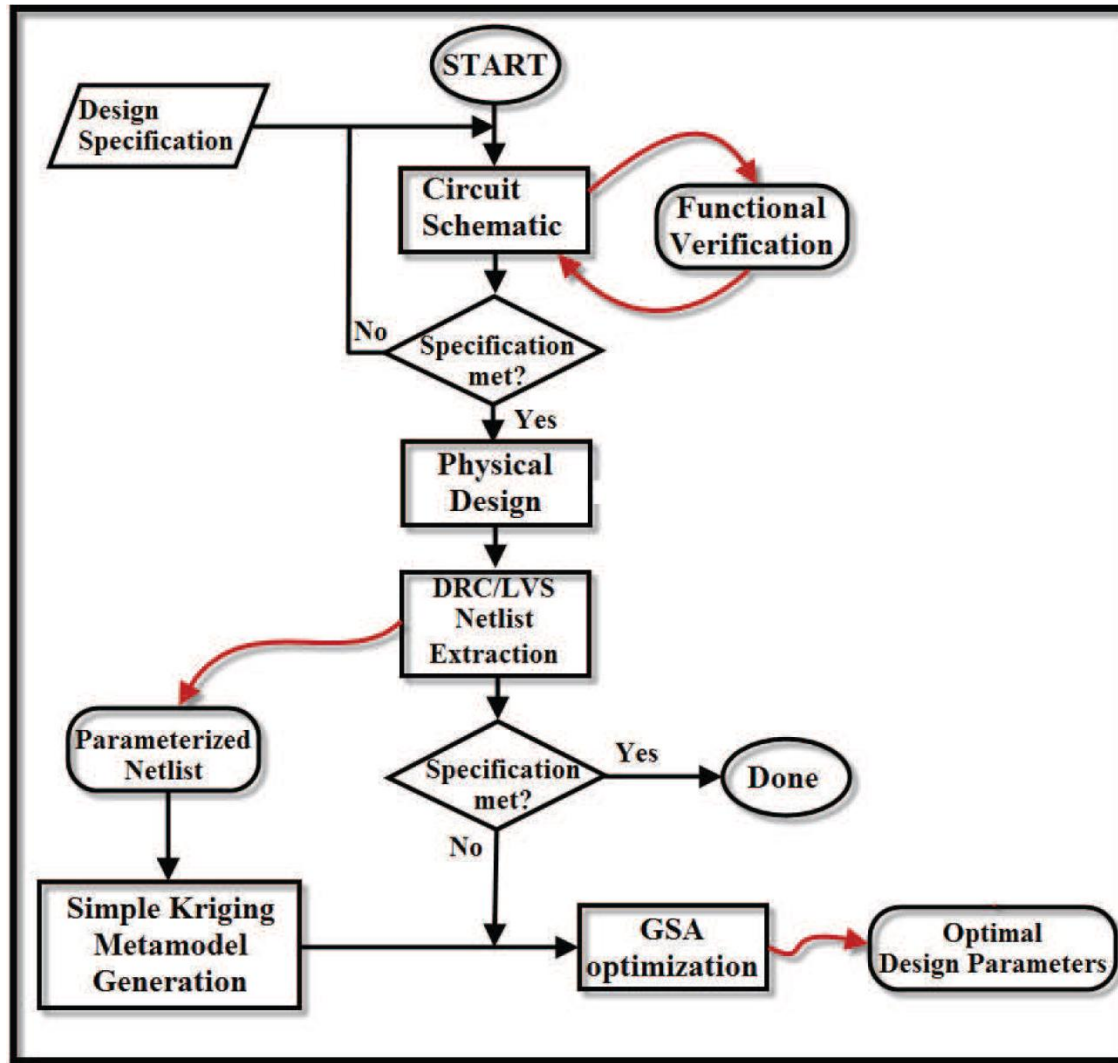
Novel Contributions

- Design flow methodology with geostatistical based metamodeling (kriging) and Gravitational Search algorithms (GSA) for nano-CMOS design optimization
- Implementation of GSA for nano-CMOS designs
- 45nm Thermal sensor designs

Prior Related Research

- Exploration of optimization algorithms for NanoCMOS designs
 - Simulated annealing, swarm intelligence
- Efficient designs for thermal sensors
- Kriging based metamodels
 - O. Okobiah --- Ordinary and Simple kriging metamodels
 - G. Yu ---- Re-iterative pareto fronts
 - H. You --- Kriging metamodels

Proposed Design Flow Diagram



Kriging Fundamentals

■ Kriging Fundamentals

- Originally used in geostatics fields for mining purposes

$$y(\mathbf{x}_0) = \sum_{j=1}^L \lambda_j B_j(\mathbf{x}) + z(\mathbf{x})$$

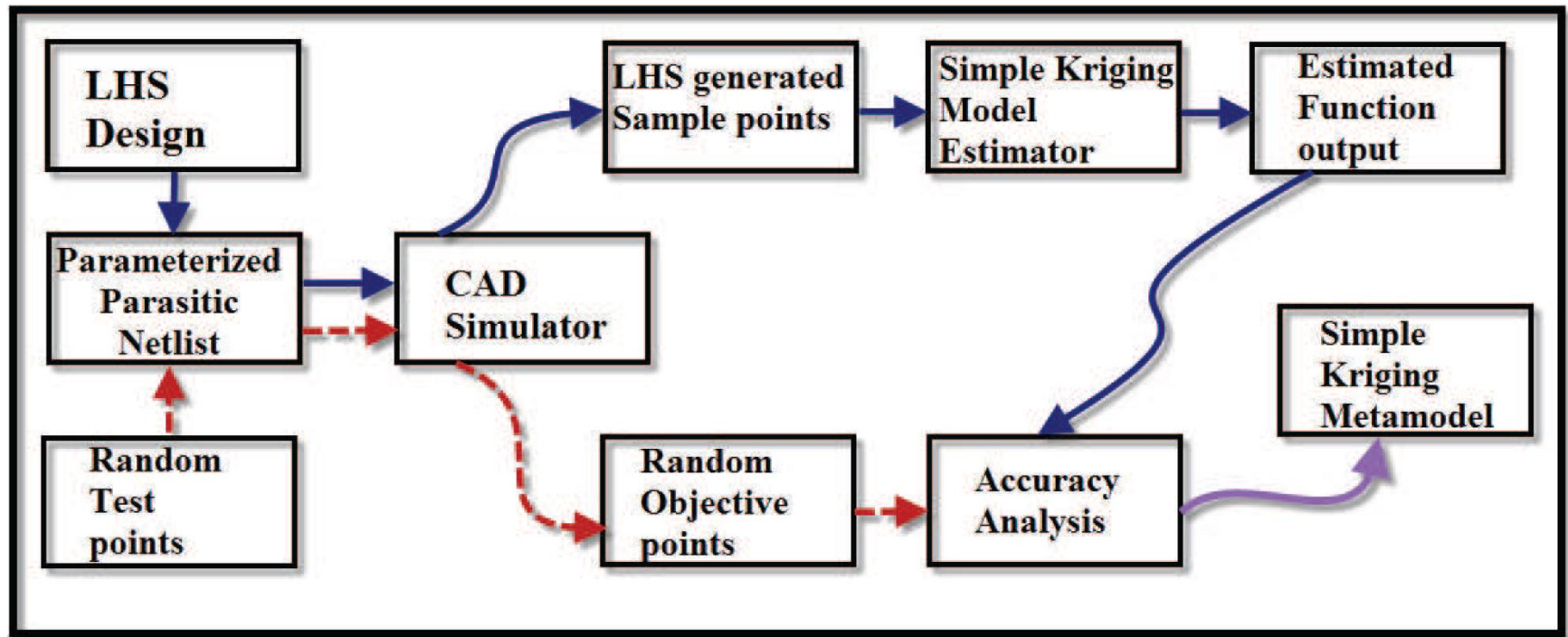
- Each point is predicted with a set of unique weights (λ_j)

Kriging Fundamentals: Ordinary Versus Simple

- Simple kriging assumes a known and local mean while ordinary kriging assumes a constant but unknown mean
- Ordinary kriging weights are biased,

$$\sum_{j=1}^n \lambda_j = 1$$

Simple Kriging Metamodel Generation



Gravitational Search Algorithm ...

- Part of Swarm Intelligence family
 - population based heuristic algorithms
- Based on gravitational laws of attraction and motion

$$F_{ij}^d(t) = G(t) \left(\frac{M_{pi}(t) \times M_{aj}(t)}{R_{ij}(t) + \epsilon} \right) (x_j^d(t) - x_i^d(t))$$

- Where $F_{ij}^d(t)$ is design objective, M is the quality of solution at search location i or j , x_i is the set of design parameters at location i

Gravitational Search Algorithm

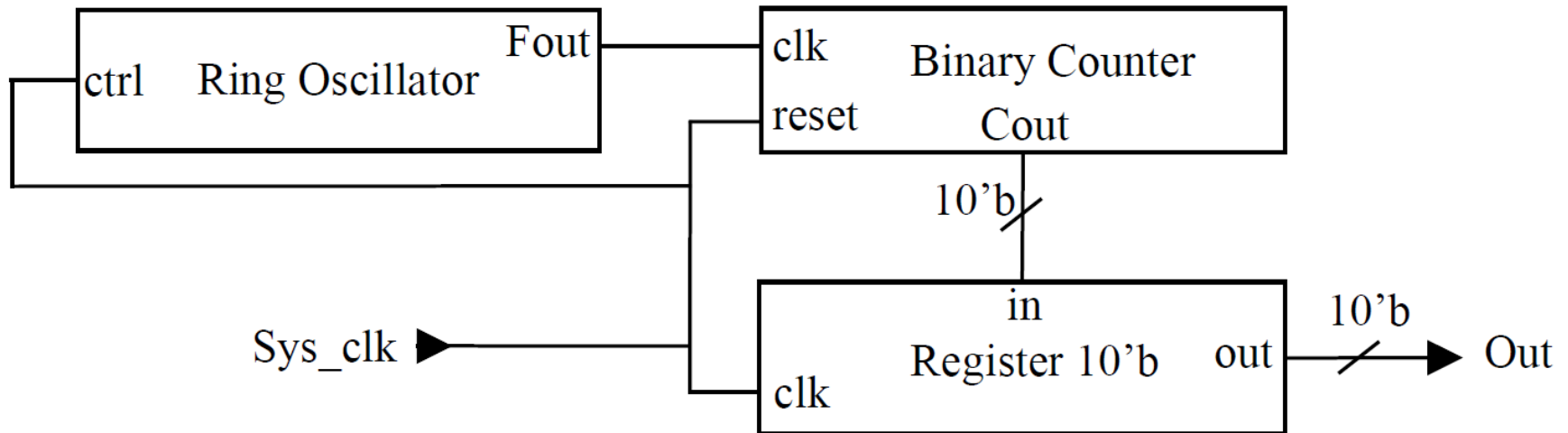
- Basic principles...
 - Heavier masses which correspond to better solutions attract search agents with poor solutions
 - Lighter masses move faster randomly -- exploring the search space
 - Heavier masses move slowly exploiting possible optimal locations

Gravitational Search Algorithm

Algorithm 1 Proposed Gravitational Search.

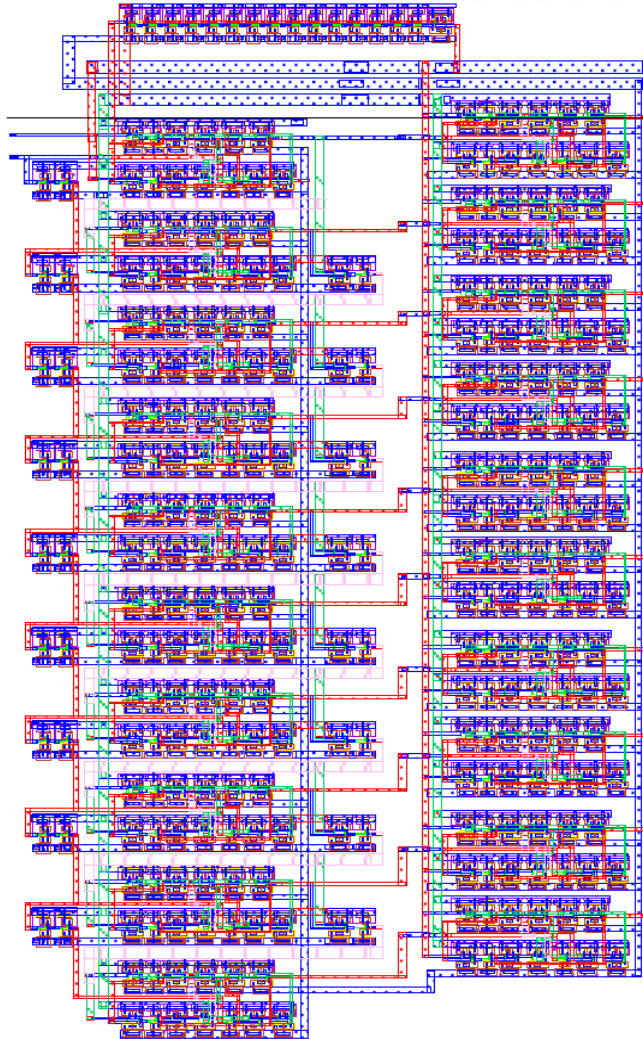
- 1: Initialize iteration counter: $counter \leftarrow 0$.
 - 2: Initialize max iteration Max_{iter} .
 - 3: Initialize number of search agents η gravity constant G , and velocity ν .
 - 4: Generate η random search nodes (design parameter sets).
 - 5: Consider the objective of interest $Power_{TS_i}$.
 - 6: $counter \leftarrow max_Iteration$.
 - 7: **while** ($counter < Max_{iter}$) **do**
 - 8: Evaluate objective of interest ($Power_{TS_i}$) for each search node.
 - 9: Update best and worst solution per function objective.
 - 10: Update the gravity constant G .
 - 11: Calculate M and a for each search node.
 - 12: Update ν for each search node.
 - 13: Update search nodes by applying velocity on M .
 - 14: $counter \leftarrow counter + 1$.
 - 15: **end while**
 - 16: **return** $bestsolution$.
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Experimental Results: 45nm Thermal Sensor

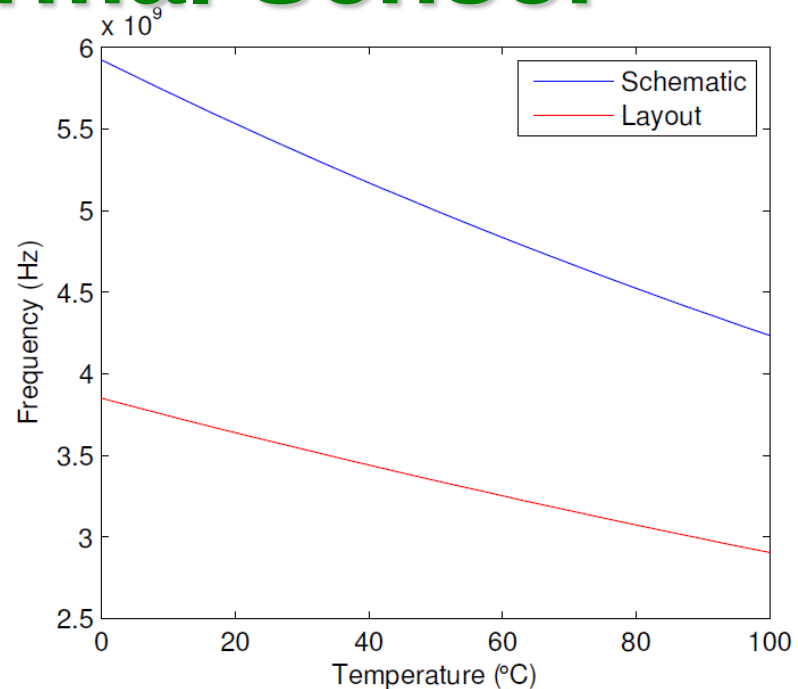


- ❑ Ring Oscillators for sensing
- ❑ Binary Counter
- ❑ Register

45nm Thermal Sensor



45nm thermal sensor physical design



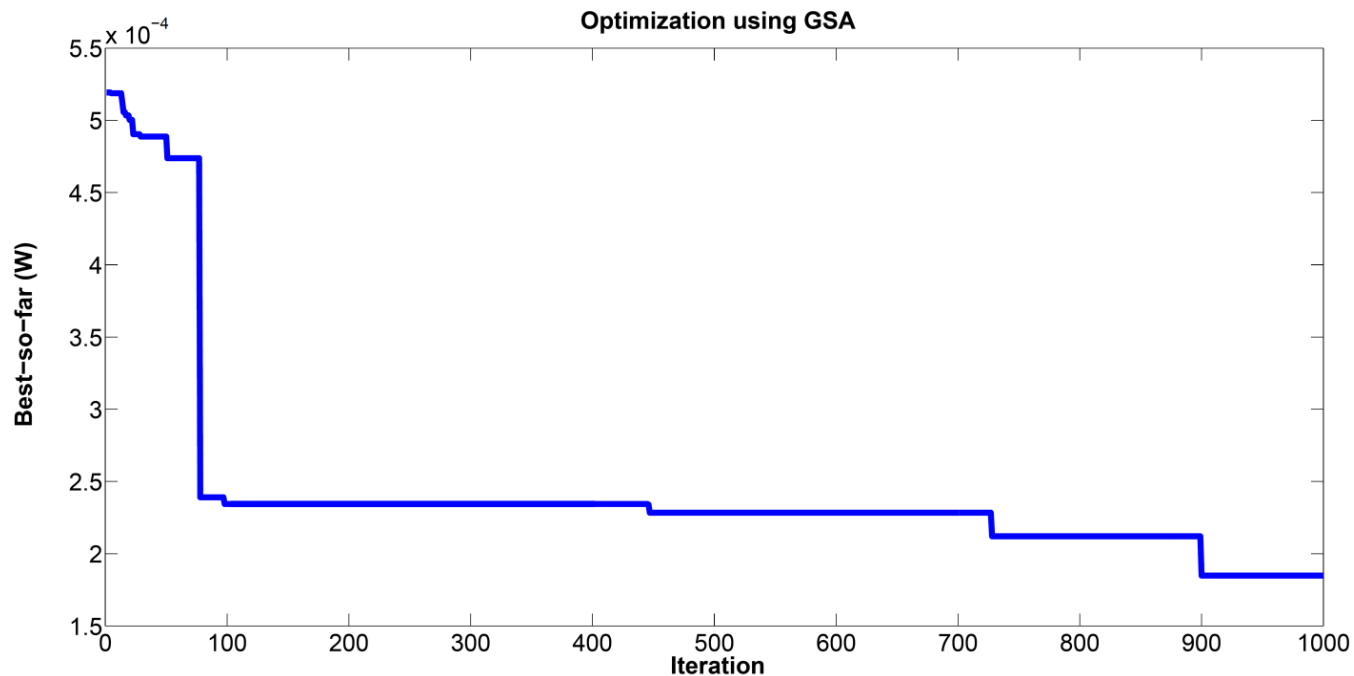
Frequency response vs temperature for 45nm thermal sensor

Design	Avg Pwr	Sensitivity	Area
Schematic	293.1μW	16.88MHz/°C	-
Layout	379.4μW	9.42MHz/°C	1221.37μm ²
% Change	+29%	-44%	

Experimental Results

Accuracy Analysis of Simple Kriging Metamodel

Metric	Value
MSE	4.36×10^{-18}
RMSE	2.09×10^{-09}
R_2	0.9934



Optimal Design Results

Design	Average Power	Sensitivity	Area
Schematic	293.1 μ W	16.88MHz/ $^{\circ}$ C	-
Layout	379.4 μ W	9.42MHz/ $^{\circ}$ C	1221.37 μ m ²
Final	+29%	9.42MHz/ $^{\circ}$ C	1770.98 μ m ² *
% Change	36.9%	44.2%	45%*

Conclusions

- A novel design flow methodology incorporating simple kriging and GSA was presented.
- Average power consumption was reduced by 36.9%
- Reduced design space exploration by 90%
- Current techniques will be explored for process variation effects and statistical optimization.



Thank you !!!